EXPO Transfer Inquiry Details

_			
aaA	licatio	on No	10676155

Art Unit 2863	Class 702	Subclass 094000
ClassificationTransfer to GAU		
Request by	LE, JOHN H (#78032)	
Gau*		
Class		use three digits for class
Subclass		
Reason		
Concurred by		(Examiner No.)
	Add Transfer Inquiry	Re-Print Transfer Inquiry

					Transfer History				
Transfer Inquiry	From GAU	To GAU	To Class	To Subclass	Requested By Decision By	Concurred By	Date	Reason	Status
		2863	702	094000	Docketed /		9/15/2004		
		2863	702	094000	Docketed /		7/9/2004		
Transfer to 2857	2613	2857	702	104	LEE, RICHARD J / 71286		JIZZIZUU4	image sensor calibration system	С

L Number	Hits	Search Text	DB	Time stamp
-	1	10/676155	USPAT;	2004/09/20 16:31
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
		·	IBM_TDB	
-	3	((image with sens\$3) same calibrat\$4 same (data	USPAT;	2004/09/20 11:41
		parameter)) and (alignment same (image with sens\$3) same	US-PGPUB;	
İ		(geometric with axis) same vehicle)	EPO; JPO;	
			DERWENT;	
			IBM_TDB	2004/00/00 42 50
-	3	((image with sens\$3) same calibrat\$4 same (data	USPAT;	2004/09/20 13:50
		parameter)) and (alignment same (image with sens\$3)) and	US-PGPUB;	
}		((geometric with axis) same vehicle)	EPO; JPO;	
			DERWENT;	
	1	(((image with const2) came calibrated came (data	IBM_TDB USPAT;	2004/09/20 12:24
-	1	(((image with sens\$3) same calibrat\$4 same (data parameter)) and (alignment same (image with sens\$3)))	US-PGPUB;	2007/03/20 12.27
		and ((geometric with travel) same vehicle)	EPO; JPO;	
		and ((geometric with traver) same vehicle)	DERWENT;	
		·	IBM_TDB	
_	6	(((image with sens\$3) same calibrat\$4 same (data	USPAT;	2004/09/20 13:00
	•	parameter)) and (alignment same (image with sens\$3))	US-PGPUB;	200 1,05/20 20:00
		and (geometric same vehicle)	EPO; JPO;	
		(3	DERWENT;	
]			IBM_TDB	
-	59	702/\$.ccls. and ((image with sens\$3) same calibrat\$4 same	USPAT;	2004/09/21 13:38
		(data parameter))	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	6	(702/\$.ccls. and ((image with sens\$3) same calibrat\$4 same	USPAT;	2004/09/22 09:47
		(data parameter))) and (alignment same (image with	US-PGPUB;	
		sens\$3))	EPO; JPO;	
			DERWENT;	
	20	(702/t cels, and ((image) with sense(2) same calibrate(4 same	IBM_TDB USPAT;	2004/09/20 13:49
-	20	(702/\$.ccls. and ((image with sens\$3) same calibrat\$4 same (data parameter))) and (adjust\$6 same (image with	US-PGPUB;	2007/03/20 13.43
		(data parameter))) and (adjustso same (image with	EPO; JPO;	
		- 3G13ψ3/)	DERWENT;	
			IBM_TDB	
-	5	((702/\$.ccls. and ((image with sens\$3) same calibrat\$4	USPAT;	2004/09/21 19:11
		same (data parameter))) and (adjust\$6 same (image with	US-PGPUB;	
		sens\$3))) and geometric and vehicle	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	2	EP-1120746-\$.did.	USPAT;	2004/09/21 15:40
			US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
		702 th sale and (Conservation 1915 1914 1914 1914 1914 1914 1914 1914	IBM_TDB	2004/00/24 42:42
-	4	702/\$.ccls. and ((image with sens\$3) same calibrat\$4 same	USPAT;	2004/09/21 13:46
		(data parameter)) and (adjust\$6 with image with sens\$3)	US-PGPUB;	
		and vehicle	EPO; JPO;	
			DERWENT; IBM_TDB	
	10	(image with sens\$3) same calibrat\$4 same (data parameter)	USPAT;	2004/09/21 14:39
-	10	and (adjust\$6 with image with sens\$3) and vehicle	US-PGPUB;	2007/03/21 17.33
		and (adjusting with image with sensps) and vehicle	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
	<u> </u>	L	100 100	

-	3	((image with sens\$3) same calibrat\$4 same (data	USPAT;	2004/09/21 14:35
		parameter) and (adjust\$6 with image with sens\$3) and	US-PGPUB;	
		vehicle) and geometric\$6	EPO; JPO;	
	1		DERWENT;	
			IBM_TDB	
_	1 1	((adjust\$6 align\$6) with image with sens\$3) same	USPAT;	2004/09/21 14:41
}	*	(geometric\$6 with travel with vehicle)	US-PGPUB;	2001/05/21 1111
		(geometricato with draver with vehicle)		
			EPO; JPO;	
		·	DERWENT;	
	_		IBM_TDB	
-	5	((adjust\$6 align\$6) with image with sens\$3) same	USPAT;	2004/09/21 15:40
		(geometric\$6 with vehicle)	US-PGPUB;	
]		EPO; JPO;	
			DERWENT;	
			IBM_TDB	
_	1	((adjust\$6 align\$6) with image with sens\$3) and	USPAT;	2004/09/21 18:26
1	•	(geometric\$6 with vehicle with (travel\$6 or mov\$6))	US-PGPUB;	200 1, 05, 22 20.20
		(geometrica with vehicle with (travelación movacy)	EPO; JPO;	
_				
			DERWENT;	
			IBM_TDB	
-	58	((adjust\$6 align\$6) with position with image with sens\$3)	USPAT;	2004/09/21 15:51
		and (vehicle with (travel\$6 or mov\$6))	US-PGPUB;	
			EPO; JPO;	
		•	DERWENT;	
			IBM TDB	
_	3	(((adjust\$6 align\$6) with position with image with sens\$3)	USPAT;	2004/09/21 15:43
	,	and (vehicle with (travel\$6 or mov\$6))) and ((evalu\$6	US-PGPUB;	2001/05/21 15:15
		estimat\$6) with image with data)	EPO; JPO;	
			DÉRWENT;	
	•		IBM_TDB	
-	15	((adjust\$6 align\$6) with position with ((image with sens\$3)	USPAT;	2004/09/21 20:45
		or camera)) and (vehicle with (travel\$6 or mov\$6)) and	US-PGPUB;	
Ì		((evalu\$6 estimat\$6) with image with data)	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
_	2	(geometric\$6 adj travel\$6 adj axis) and vehicle	USPAT;	2004/09/21 18:27
	_		US-PGPUB;	
	İ		EPO; JPO;	
			DERWENT;	
		///anamakulah@ wikh kumunlh@ with aut=\ and wahinla\ = = d	IBM_TDB	2004/00/21 10:00
-	1	(((geometric\$6 with travel\$6 with axis) and vehicle) and	USPAT;	2004/09/21 19:00
		(image near2 sensor)) and ((align\$6 or adjust\$6) with	US-PGPUB;	
		position with (image near2 sensor))	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	39	(((geometric\$6 with travel\$6 with axis) and vehicle) and	USPAT;	2004/09/21 18:31
		(image near2 sensor)) and ((align\$6 or adjust\$6) with	US-PGPUB;	
		(image near2 sensor))	EPO; JPO;	
		\	DERWENT;	
			IBM_TDB	
	41	((geometric\$6 with travel\$6 with axis) and vehicle) and	USPAT;	2004/09/21 18:32
1	41			2007/03/21 10.32
	1	(image near2 sensor)	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	5	((adjust\$6 align\$6) with position with ((image with sens\$3)	USPAT;	2004/09/21 18:35
		or camera)) and (vehicle with (travel\$6 or mov\$6)) and	US-PGPUB;]
		((evalu\$6 estimat\$6) with image with data) and (angle with	EPO; JPO;	
		measur\$6)	DERWENT;	1
			IBM_TDB	
L	1	l		

			r	
] -	2	(((geometric\$6 near2 (travel\$6 driv\$3) near2 axis) and	USPAT;	2004/09/21 19:01
		vehicle) and (image near2 sensor)) and ((align\$6 or	US-PGPUB;	
		adjust\$6) with position with (image near2 sensor))	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	3	(((geometric\$6 near2 (travel\$6 driv\$3) near2 axis) and	USPAT;	2004/09/21 19:01
		vehicle) and (image near2 sensor)) and ((align\$6 or	US-PGPUB;	
	•	adjust\$6) with (image near2 sensor))	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	1	(intrinsic with calibration with data) and (camera with	USPAT;	2004/09/21 20:49
		principal with point) and (camera with principal with	US-PGPUB;	
1		distance) and (distortion with parameter) and (glass with	EPO; JPO;	
		pane)	DERWENT;	
			IBM_TDB	
-	1	(intrinsic with calibration with data) and (camera with	USPAT;	2004/09/21 20:48
		principal with point) and (camera with principal with	US-PGPUB;	
	-	distance) and (glass with pane)	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	1	(intrinsic with calibration with data) and (camera with	USPAT;	2004/09/21 20:48
		principal with point) and (camera with principal with	US-PGPUB;	
		distance)	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	1	(intrinsic with calibration with data) and (camera with	USPAT;	2004/09/21 20:50
		point) and (camera with distance) and (distortion with	US-PGPUB;	
		parameter) and (glass with pane)	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
	1	(intrinsic with calibration with data) and (camera with	USPAT;	2004/09/21 20:50
		point) and (camera with distance) and (distortion with	US-PGPUB;	
		parameter) and glass	EPO; JPO;	
1			DERWENT;	
		(#4452064# #4226704# #4700040# #4054067#	IBM_TDB	2004/00/22 00 42
-	11	("4152061" "4236794" "4789940" "4954962"	USPAT	2004/09/22 09:42
		"5036474" "5101277" "5170352" "5307170"		
		"5400383" "5453845" "5460312").PN.	LICDAT	2004/00/22 00:47
-	0	(("4152061" "4236794" "4789940" "4954962"	USPAT	2004/09/22 09:47
		"5036474" "5101277" "5170352" "5307170"		
		"5400383" "5453845" "5460312").PN.) and (glass near2		
	0	pane) (("4152061" "4236704" "4780040" "4054062"	LICDAT	2004/09/22 09:48
-		(("4152061" "4236794" "4789940" "4954962" "5036474" "5101277" "5170352" "5307170"	USPAT	בטטדן טאן בע טאיי אלי
		3036474 3101277 3170352 3307170 "5400383" "5453845" "5460312").PN.) and (influence		
		with glass)		
l <u>.</u>	4	("4692806" "5134473" "5270756" "5296926").PN.	USPAT	2004/09/22 09:44
l <u>.</u>	0	(("4692806" "5134473" "5270756" "5296926").PN.) and	USPAT	2004/09/22 09:44
		((4052000 5154475 5270750 5250520).FN.) and (glass near2 pane)	33, A1	200 1/03/22 03.77
-	0	(("4692806" "5134473" "5270756" "5296926").PN.) and	USPAT	2004/09/22 09:44
ł		(influence with glass)	···	
-	7	("5068791" "5247487" "5949685" "6047234"	USPAT	2004/09/22 09:47
	-	"6226571" "6275773" "6292752").PN.	=	, , , , , , , , , , , , , , , , , , , ,
-	О	(("5068791" "5247487" "5949685" "6047234"	USPAT .	2004/09/22 09:48
		"6226571" "6275773" "6292752").PN.) and (glass near2		, ,
		pane)		
-	0	(("5068791" "5247487" "5949685" "6047234"	USPAT	2004/09/22 09:48
		"6226571" "6275773" "6292752").PN.) and (influence		
		with glass)		·
		<u> </u>	· · · · · · · · · · · · · · · · · · ·	·